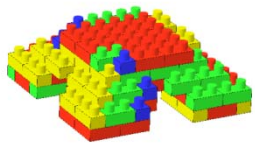
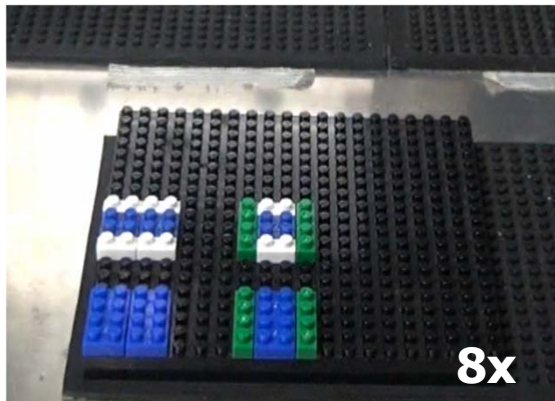


From CAD Models to Toy Brick Sculptures: A 3D Block Printer

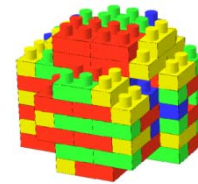
Yusuke MAEDA, Ojiro NAKANO, Takashi MAEKAWA
and Shoji MARUO (Yokohama National University, JAPAN)



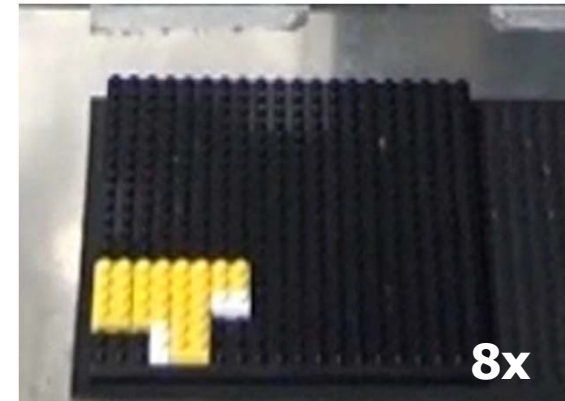
#blocks: 104



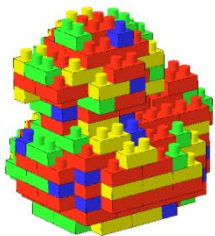
8x



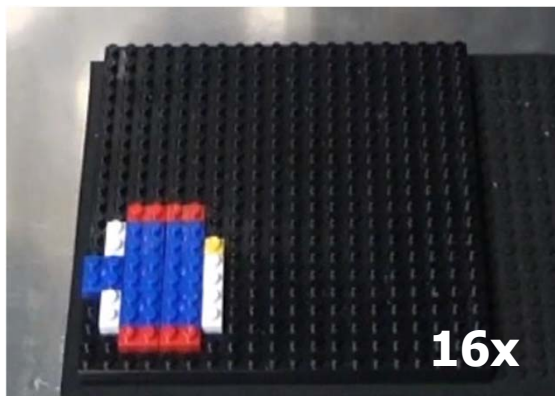
#blocks: 95



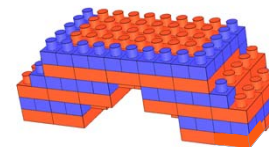
8x



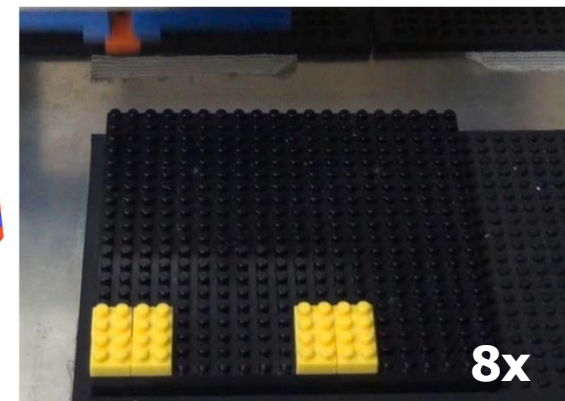
#blocks: 191



16x



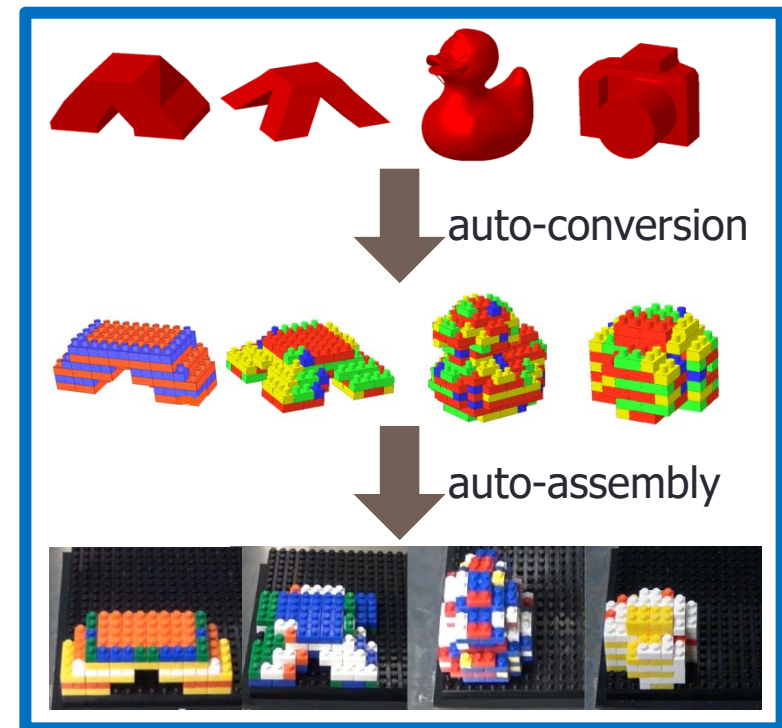
#blocks: 118



8x

Overview

- A robotic 3D printer that uses toy bricks as digital material is presented
- A 3D CAD model is automatically converted into a block model consisting of primitive blocks
- An assembly plan of the block model is automatically generated
- A toy brick sculpture is automatically assembled layer by layer according to the plan by a robot

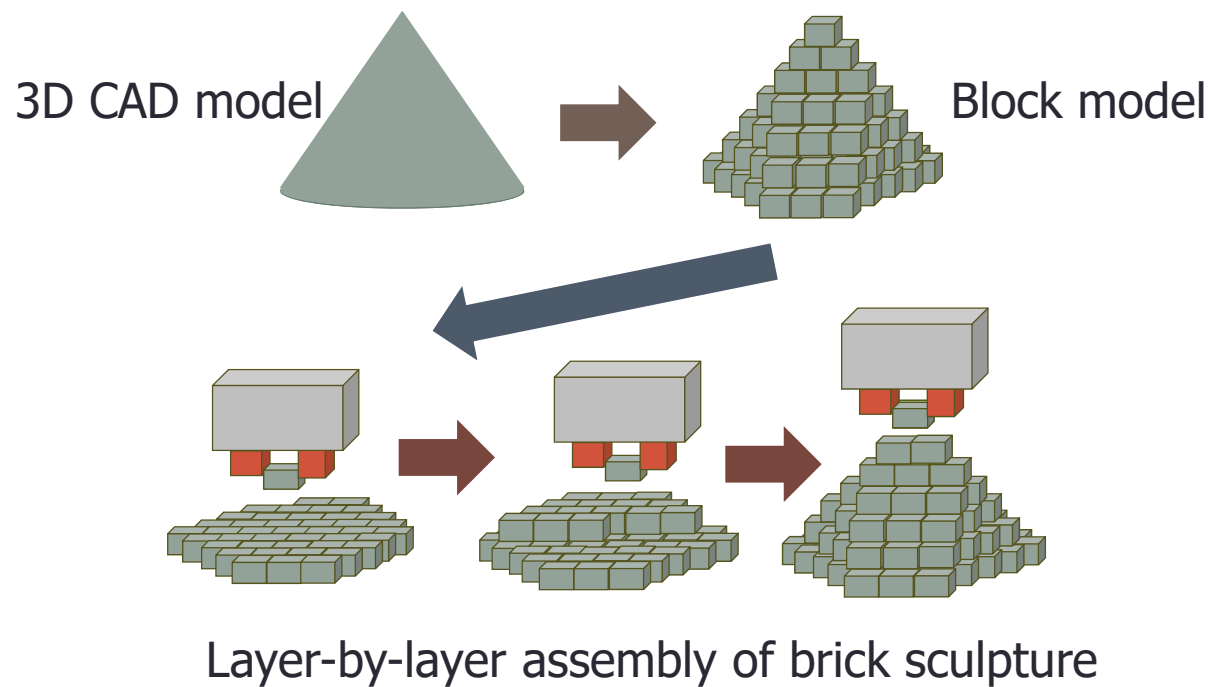


Background

- Digital materials including LEGO-like blocks can be used for additive manufacturing
 - “Voxel Printing” [Hiller and Lipson 2009]
 - Perfect repeatability
 - Multiple materials
 - Smart voxels
 - ...

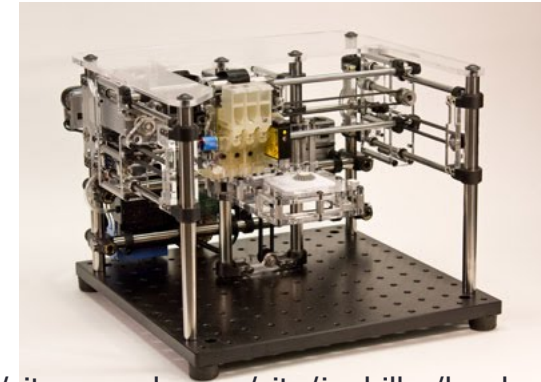
Objective

- To develop a robot system that assembles LEGO-like toy blocks to produce brick sculptures

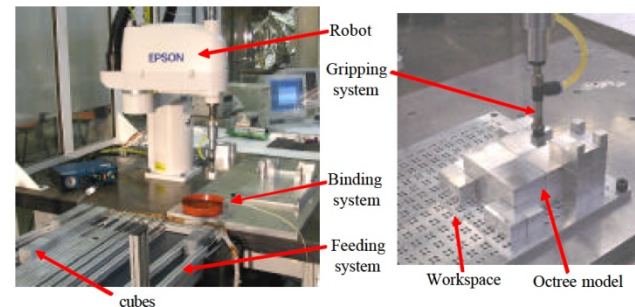


Related works

- A “VoxJet” Printer with spherical voxels [Hiller and Lipson 2009]
- A SCARA robot that assembles cubes with gluing [Medellin et al. 2010]
- A parallel robot that assembles truncated octahedra with magnetic connectors (“Kelvin blocks”) [Sekijima et al. 2015]
- ...



<https://sites.google.com/site/jonhiller/hardware/rapid-assemblers/voxjet>



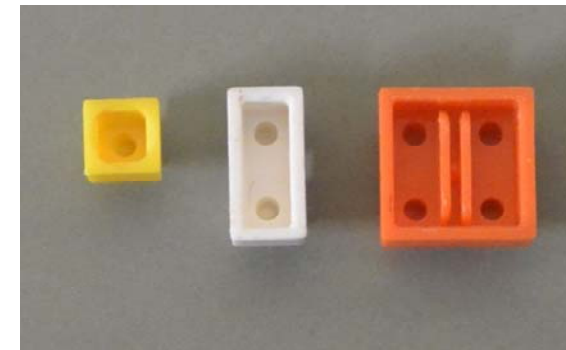
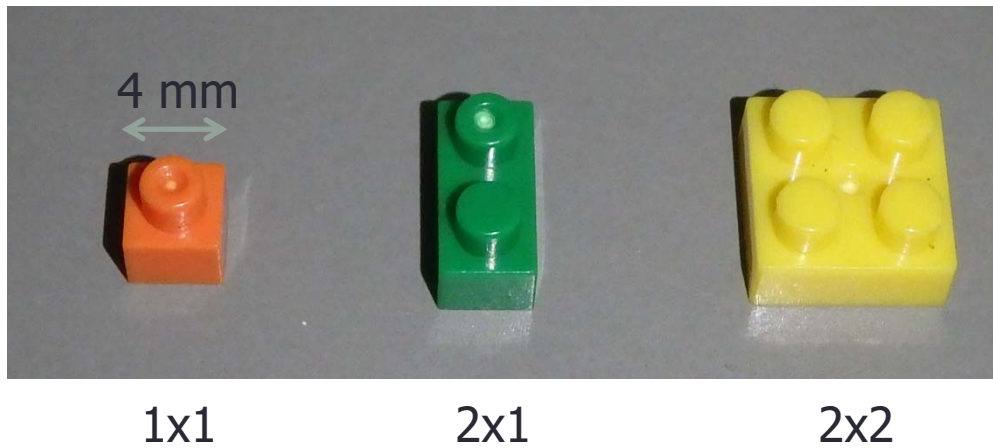
https://pure.strath.ac.uk/portal/files/365120/Automatic_generation_of_robot_and_manual_assembly_plans.pdf



<http://fab.sfc.keio.ac.jp/?projects=kelvin-block>

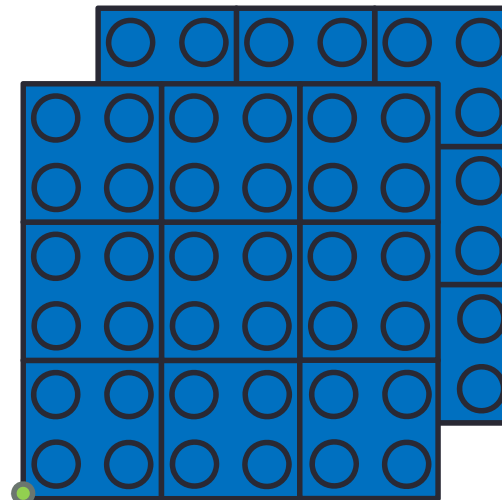
Building blocks

- “nanoblock” by Kawada



Conversion from a 3D CAD model to a block model

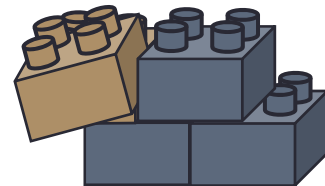
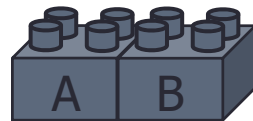
- An automatic conversion method [Kozaki et al. 2016] is adopted
 - A 3D CAD model in OFF (Object File Format) is converted to unit voxels with edge length ratio of 4:4:3
 - Then the voxels are replaced by the primitive blocks so that the number of blocks are reduced using simulated annealing
 - The reference point for the replacement is shifted one unit in column and row directions for each layer to strengthen the assembled structure



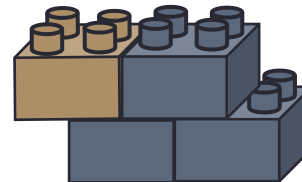
Assembly planning (1/2)

- Assembly success depends on the order of block placement

A → B

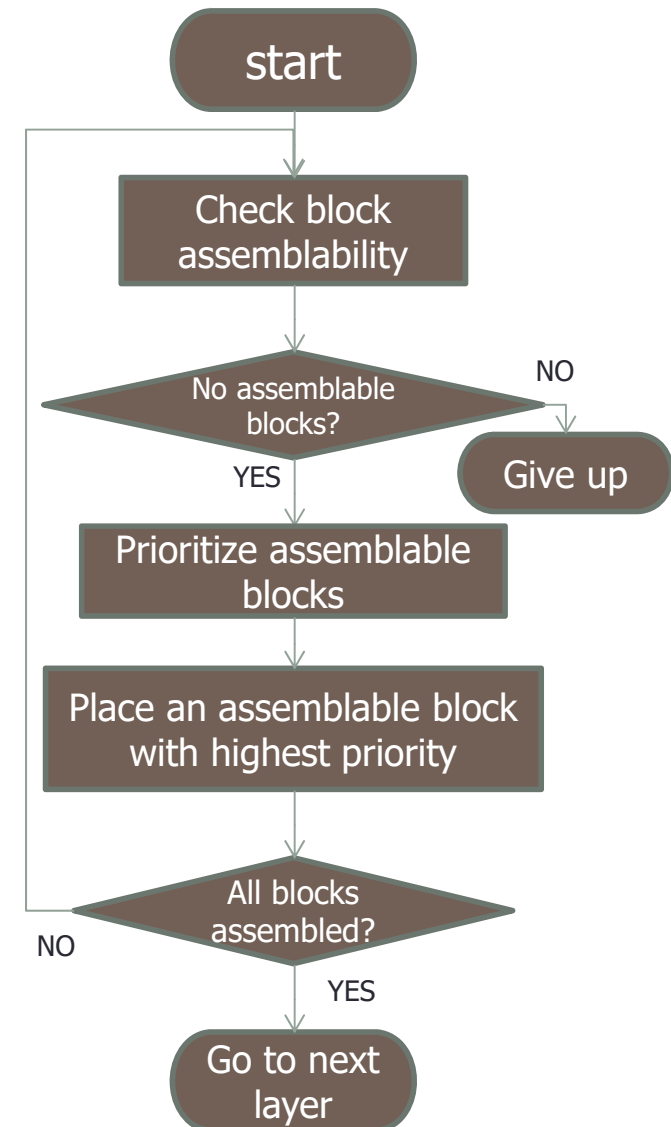


B → A

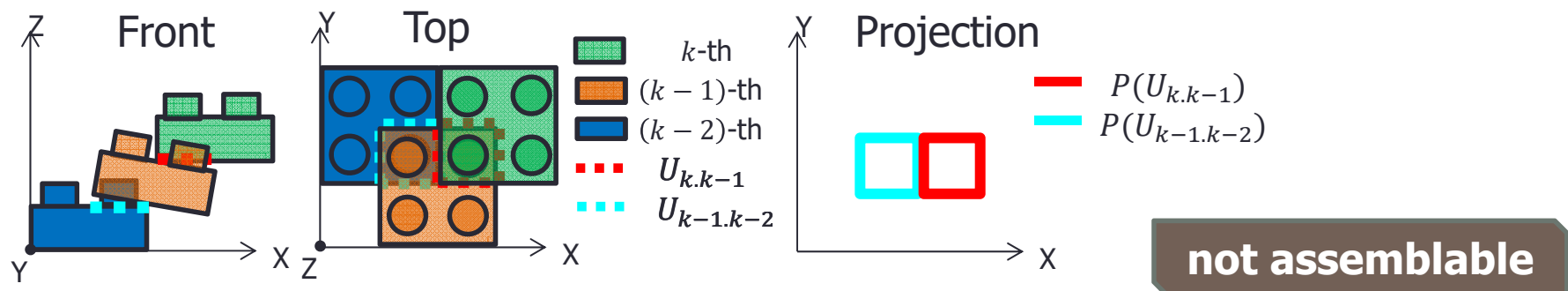
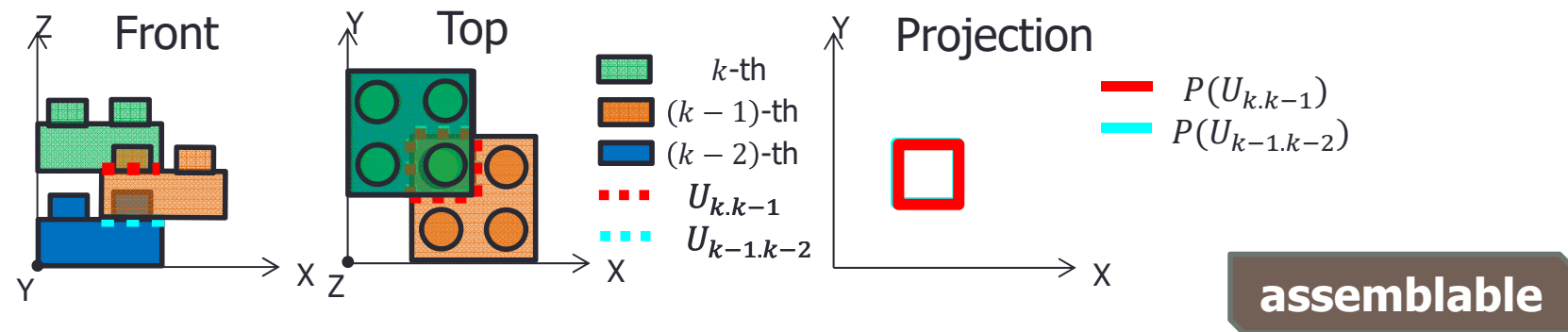


Assembly planning (2/2)

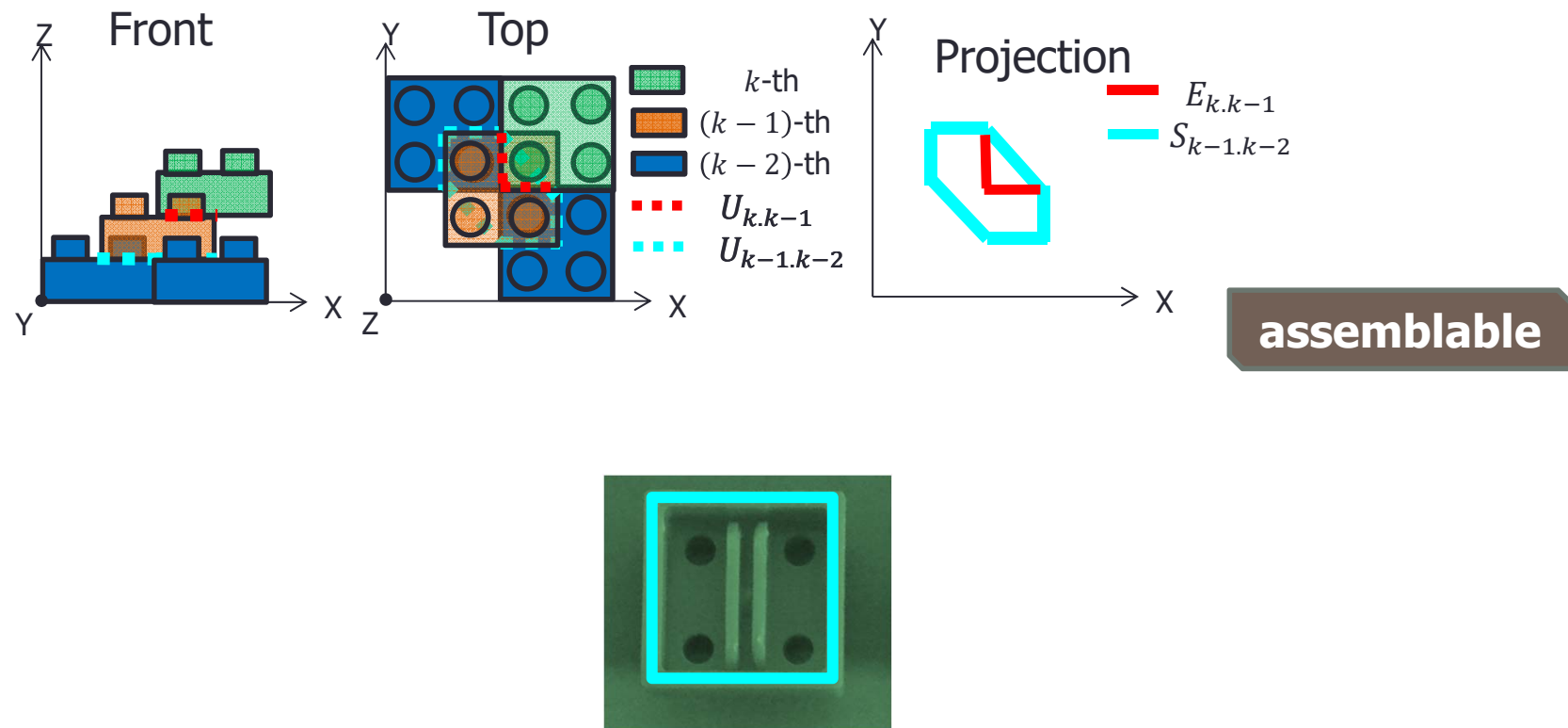
- Assumption
 - Bottom-to-top, layer-by-layer assembly
 - Block placement by vertical insertion
- Assembly planning requires:
 - Block assemblability check
 - In-layer block placement ordering



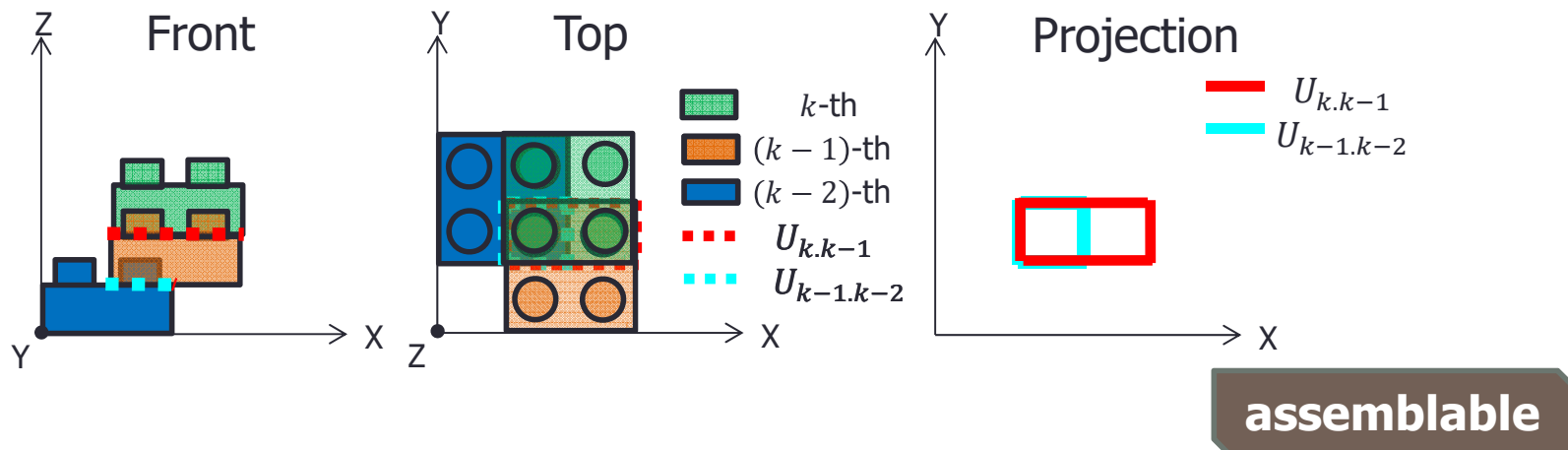
Block assemblability check: Contact region inclusion



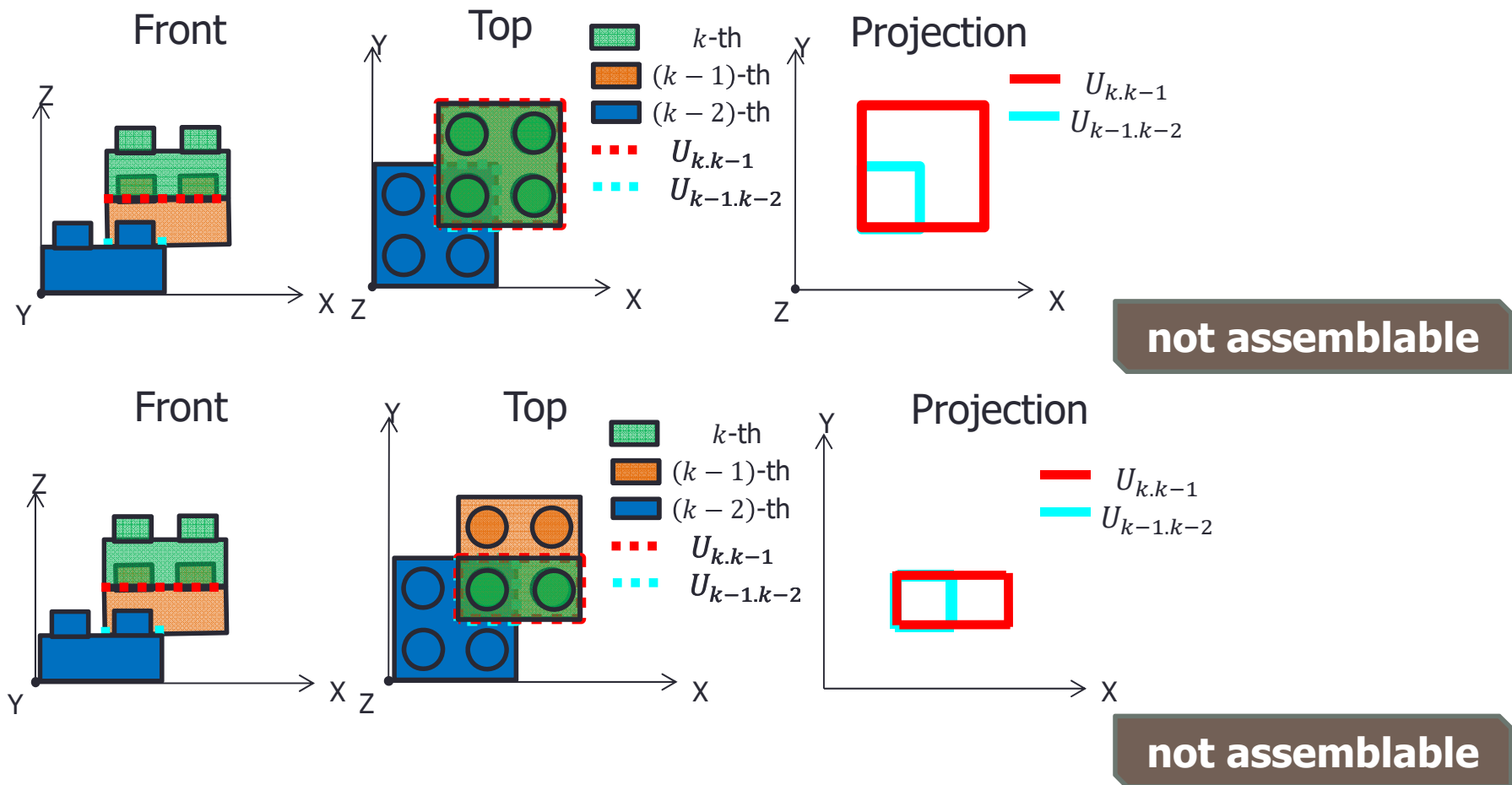
Block assemblability check: Contact edge inclusion



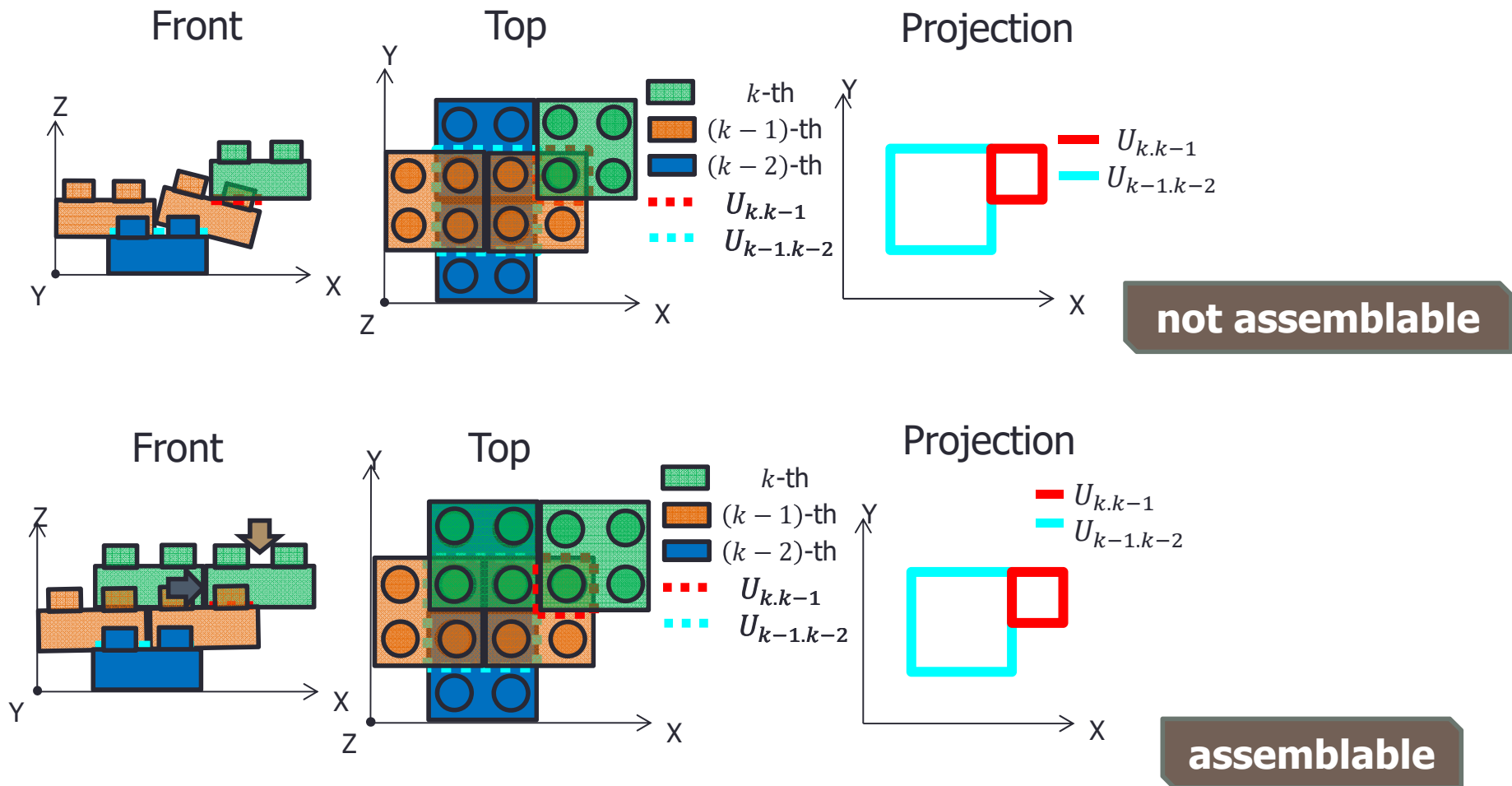
Block assemblability check: Multi-stud connection (1/2)



Block assemblability check: Multi-stud connection (2/2)

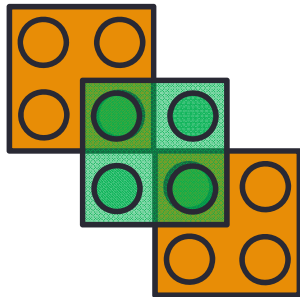


Change of block assemblability

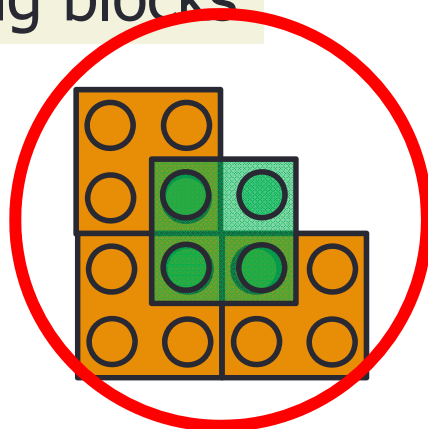


Block placement ordering: Prioritization

of connecting blocks

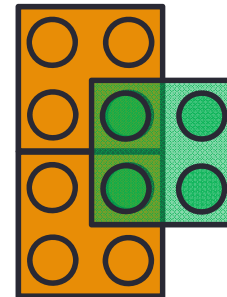


Connects two blocks

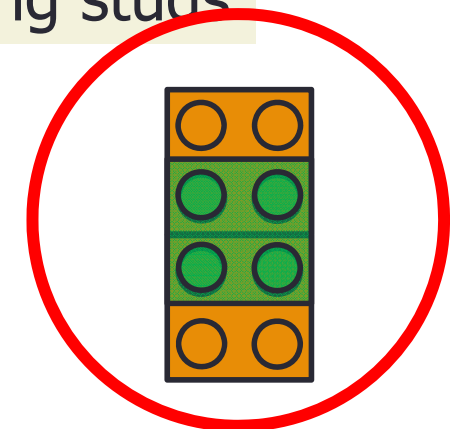


Connects three blocks

of connecting studs

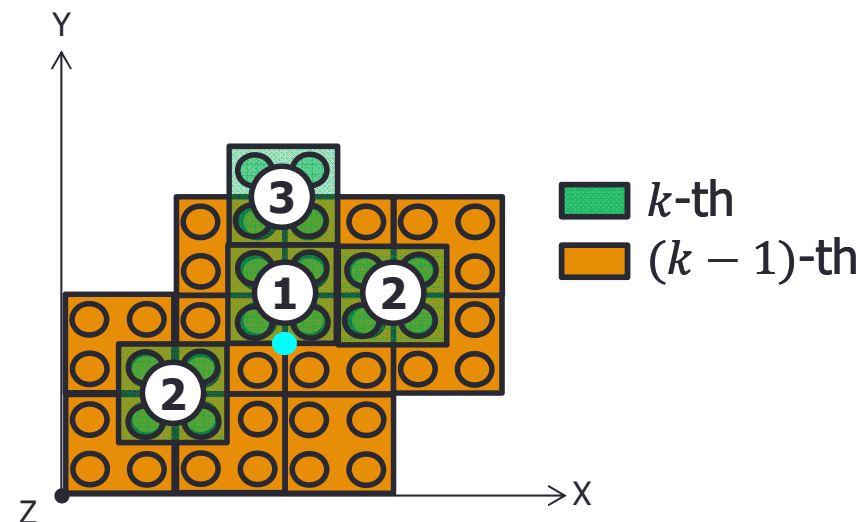


Connects with two studs

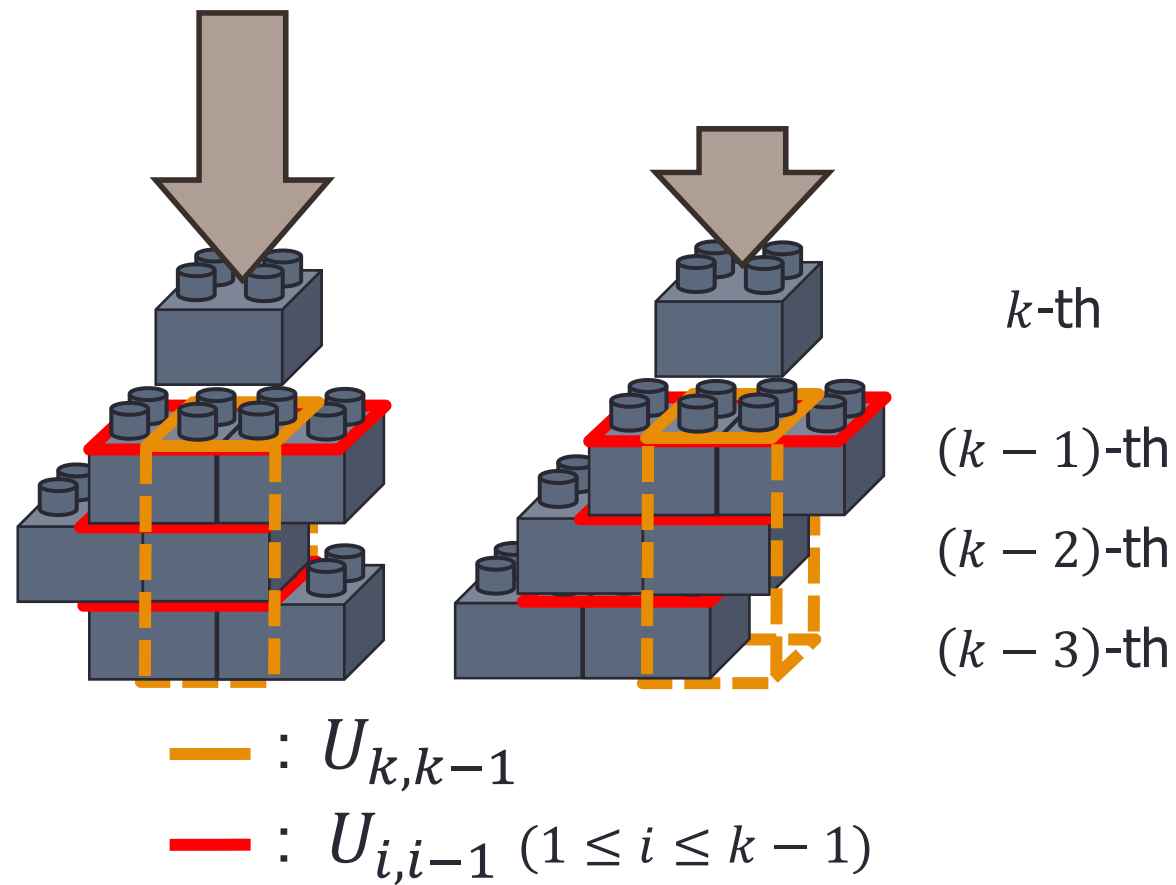


Connects with four studs

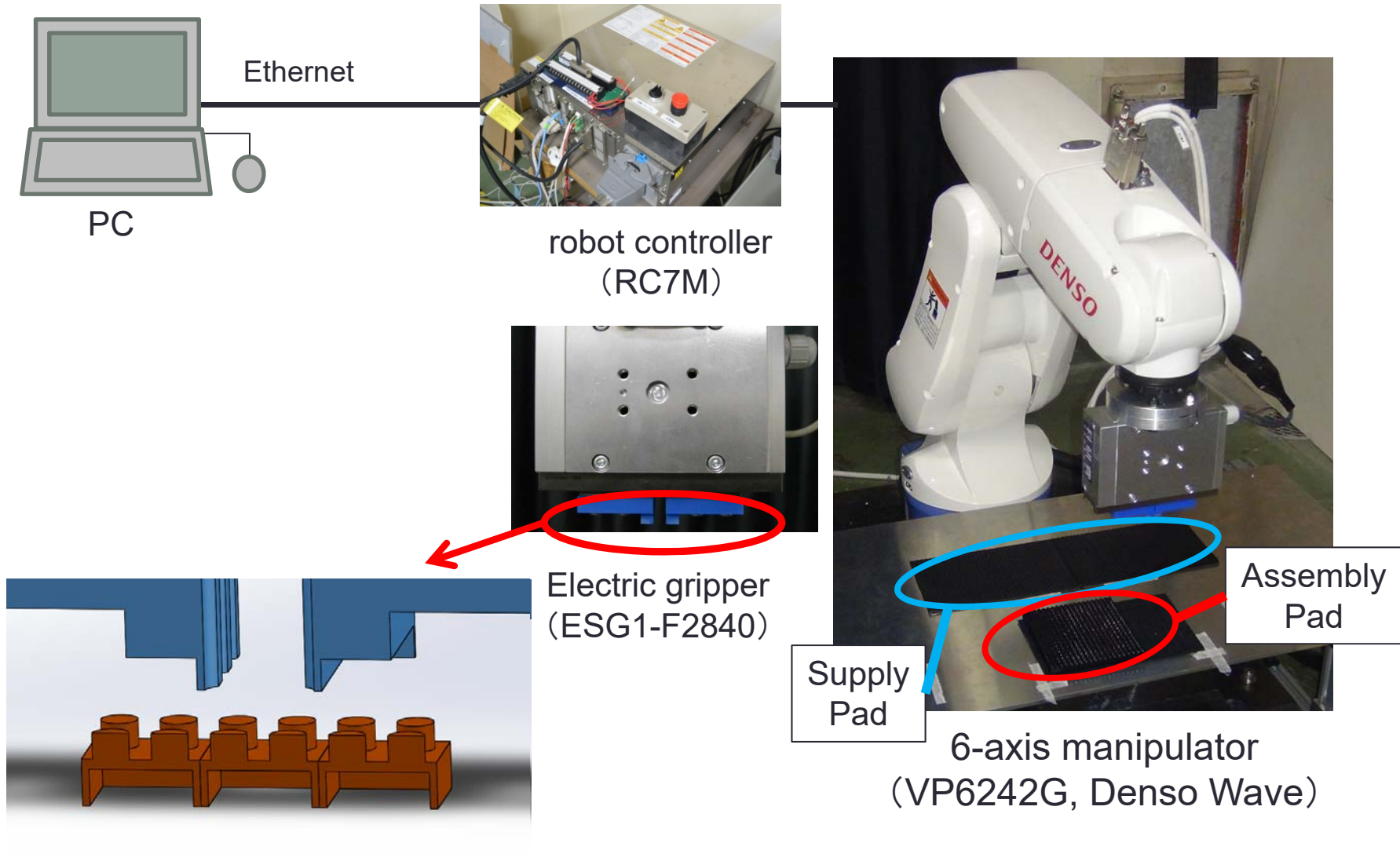
Inter-centroid distance



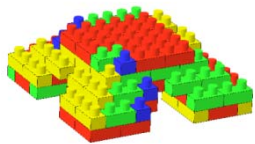
Force control in assembly



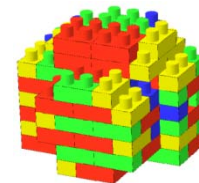
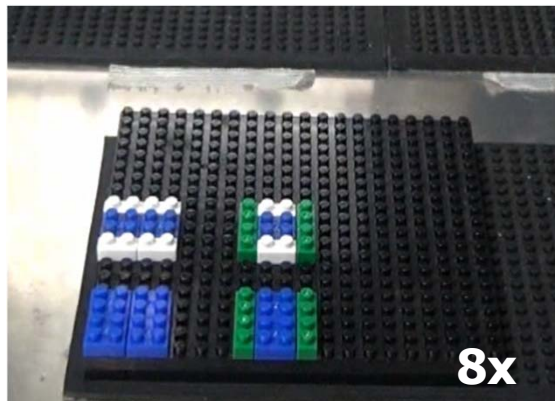
Experimental Setup



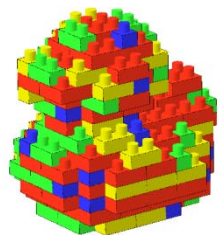
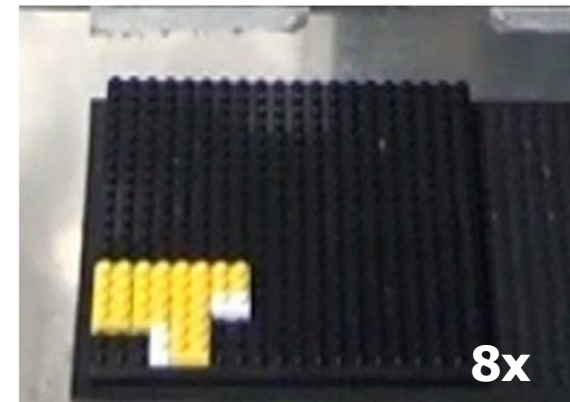
Assembly experiments



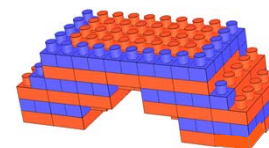
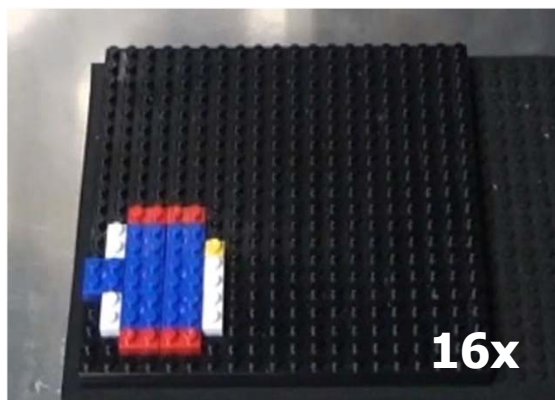
#blocks: 104



#blocks: 95



#blocks: 191



#blocks: 118

